AMET 18 MICRO PROCESSOR

UNIT-1 MICROPROCESSOR ARCHITECTURE AND MICROCOMPUTER SYSTEM

- 1.1 Objectives, the microprocessor is a programmable logic device, designed with registers, flip-flops, and timing elements, memory, r/wm (read/write memory), rom (read-only memory),
- 1.2 Ee-prom (electrically erasable prom), recent advances in memory technology, input and output (i/o) devices,
- 1.3 Example of a microcomputer system, review logic devices for interfacing, examples of latches.

UNIT-2 8086 MICROPROCESSOR ARCHITECTURE AND MEMORY INTER-FACING

- 2.1 The 8085 mpu, address bus, multiplexed address/data bus, control and status signals, power supply and clock frequency, externally initiated signals, serial i/o ports, the alu,
- 2.2 Timing and control unit, instruction register and decoder, register array, example of an bobsbased microcomputer, memory interfacing, the sdk-85 memory system',
- 2.3 How does an 8085-based single-board microcomputer work?

UNIT-3 INTERFACING I/O DEVICES d fingineer 2nd

- 3.1 Basic interfacing concepts, out instruction (8085), in instruction, interfacing output displays, circuit analysis, program, program description, problem statement,
- 3.2 Hardware description, seven-segment led, interfacing circuit and its analysis, interfacing input devices, memory-mapped i/o, execution of memory-related data transfer instructions,
- 3.3 Output port and its address, input port and its address, testing and troubleshooting i/o interfacing circuits, some questions and answers.

UNIT-4 INTERRUPTS

- 4.1 The 8085 interrupt, rst (restart) instructions, problem statement, main program, description of the interrupt process, testing interrupt on a single-board computer system,
- 4.2 Issues in implementing interrupts, 8085 vectored interrupts, trap, rst 7.5, 6.5, and 5.5, triggering levels, pending interrupts, problem statement, hardware description,
- 4.3 Monitor program, main program, program description, internet service routine, restart as software instructions, problem statement, problem analysis, breakpoint subroutine,
- 4.4 Program description, additional I/O concepts and processes, 8259a interrupt operation.

UNIT-5 INTERFACING DATA CONVERTERS

- 5.1 Digital-to-analog (d/a) converters, r/2r ladder network, problem statement, hardware description, program, operating the d/a converter in a bipolar range,
- 5.2 Hardware description, analog-to-digital (aid) converters, interfacing an 8-bit a/d converter using status check, hardware description, interfacing circuit,
- 5.3 Service routine, dual-slope a/d converters.

UNIT-6 SDK-85 PROGRAMMABLE INTERFACE DEVICES

6.1 Basic concepts in programmable devices, data input with handshake, data output with handshake, the 8155/8156 and 8355/8755 multipurpose programmable devices,

- 6.2 Control logic, the 8155 i/o ports, chip enable logic and port addresses, control word, hardware description, control word, program description, problem statement,
- 6.3 Control signals in handshake mode, input, output, status word, problem statement, problem analysis, port addresses, program description, interrupt i/o,
- 6.4 The 8279 programmable keyboard/display interface, keyboard section, scan section, display section, mpu interface section, circuit description,
- 6.5 Decoding logic and port addresses, initialization instructions.

UNIT-7 SERIAL I/O AND DATA COMMUNICATION

- 7.1 Basic concepts in serial i/o, Synchronous vs, Asynchronous transmission, Simplex and duplex transmission, Rate of transmission (baud), Parity check, Checksum,
- 7.2 Cyclic redundancy check (crc), Software-controlled asynchronous serial i/o, Serial output data (sod), Serial input data (sid), Hardware-controlled serial i/o using programmable chips,
- 7.3 Read/write control logic and registers, Transmitter section, Receiver section, initializing the 8251a, Program description.

UNIT-8 MICROPROCESSOR APPLICATION Age 9

- 8.1 Designing scanned displays, Sn 75491-segment driver, Sn 75492-digit driver, Interfacing a matrix keyboard, Keyboard subroutine, Mm74c923 keyboard encoder, Memory design,
- 8.2 Eprom memory, Wait state calculations, 8086 mpu design, Address bus, Data bus, Control signals, Frequency and power requirements, Externally triggered signals,
- 8.3 Designing a system: single-board microcomputer, Keyboard, Display, Execute, System buses and their driving capacity, Keyboard and displays, Software design,
- 8.4 Program coding, Development and troubleshooting tools, Emulation process, Features of incircuit emulator, Debugging tools.

UNIT-10 INTRODUCTION TO 8085 ASSEMBLY LANGUAGE PROGRAMMING

- 9.1 The 8085 programming model, registers, accumulator, flags, program counter (pc), stack pointer (sp), instruction classification, data transfer (copy) operations,
- 9.2 Arithmetic operations, logical operations, branching operations, machine control operations, instruction format, one-byte instructions, two-byte instructions, three-byte instructions

Reference Books:

- 1. Krishna Kant, "Microprocessor and Microcontrollers", Eastern Company Edition, Prentice Hall of India, New Delhi, 2007.
- 2. B.RAM," Computer Fundamentals Architecture and Organization" New Age International Private Limited, Fifth edition, 2017.
- 3. Soumitra Kumar Mandal, Microprocessor & Microcontroller Architecture, Programming & Interfacing using 8085,8086,8051,McGraw Hill Edu,2013